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# **Design, implementation and control of an Intelligent Surveillance Robot Monitoring Outdoor Security**

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## Abreviation list

### **Chapter 1: general-robotics-final**

ARM	Adjustable-Rate			
				imaging
AUVs	Mortgage Autonomous underwater vehicle	NASA		National Aeronautics and Space Administration
BCR	Bell Communications Research	NMR		Nuclear magnetic resonance
CCD	Charge-Coupled Device	OTPROM		One-time programmable read-only memory.
CMOS	Complementary Metal Oxide Silicon	RAM		Random access memory
CPU	Central Processing Unit	RHIB		rigid-hulled inflatable boat
CNN	Convolutional Neural Network	RISC		Reduced instruction set computer
DSR	Dynamic Spatial Reconstructor	ROM		Read Only Memory
EER PROM	Electrically Erasable Programmable Read- Only Memory	PTZ		with pan , tilt and controllable zoom functions
EO	Ex Officio	SAR		Special Administrative Region
GPS	Global Positioning System	UAVs		unmanned aerial vehicle
ILS	Instrument Landing System	UGVs		unmanned Ground Vehicles
IR	Infrared Radiation	UUVs		unmanned undersea vehicles
L/D	Lift-to-Drag	UV PROM		Ultra Violet Programmable Read Only Memory
MTCNN	Multi-task convolutional neural network	WIFI		wireless networking technology that allows communication

## Chapter 2: Intelligent Surveillance Robots - State of Art

<i>ART</i>	Assisted Reproductive Technology	<i>GHOC</i>	Global Hawk Operations Center
<i>BLOS</i>	Boss Looking Over Shoulder	<i>ISR</i>	Intelligence, Surveillance, and Reconnaissance
<i>CEO</i>	Chief Executive Officer	<i>LBP</i>	
<i>CORBA</i>	Common Object Request Broker Architecture	<i>LOS</i>	Law Of the Sea
<i>DFRS</i>	Defence Fire and Rescue Service	<i>PC</i>	Personal Computer
<i>EAFB</i>		<i>RSTA</i>	Rockford Science and Technology Academy
		<i>UAV</i>	Unmanned Aerial Vehicle

### Abreviation list

## Chapter 3: Theoretical study and Inception

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